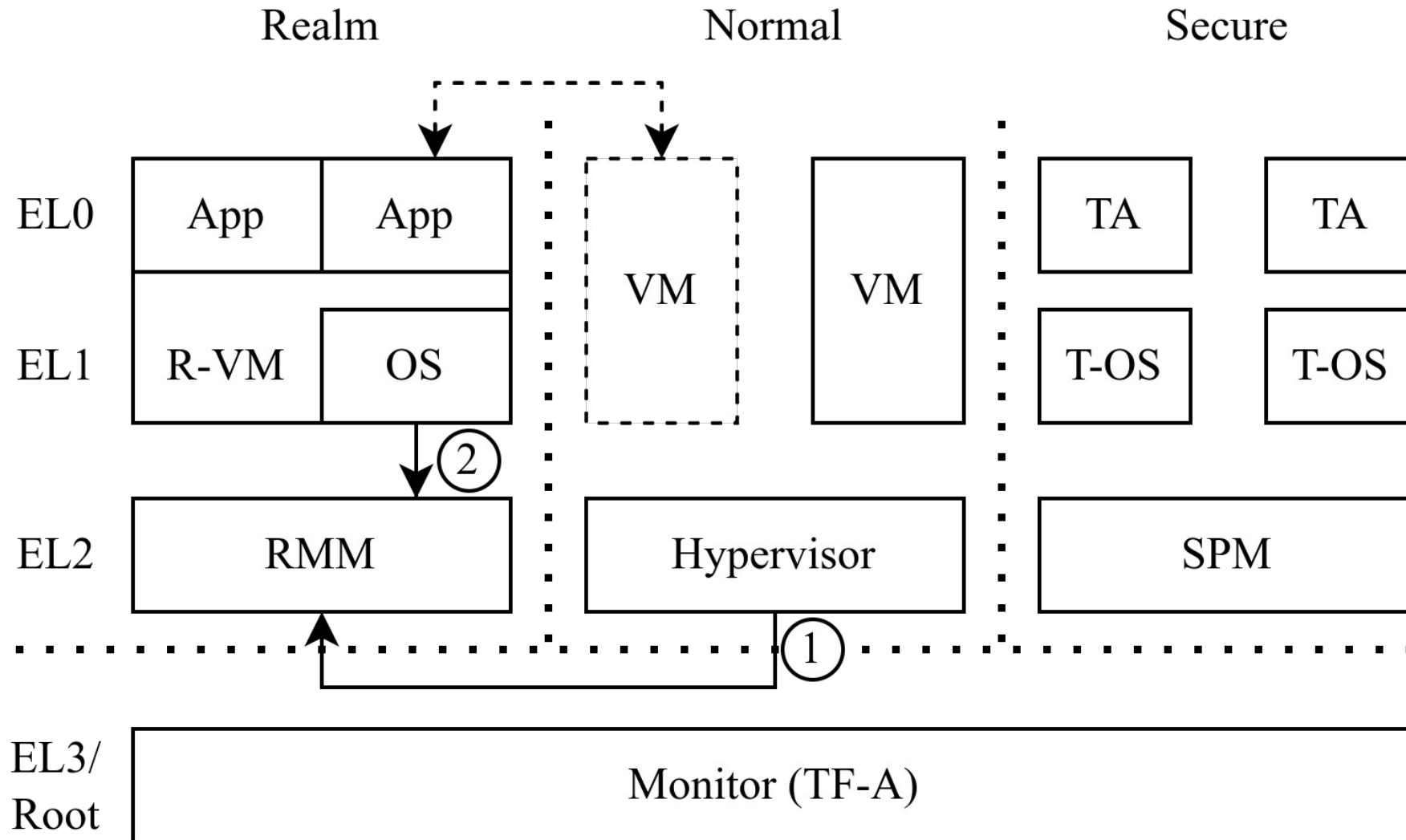


BarriCCAdo: Isolating Closed-Source Drivers with ARM CCA

Matti Schulze, Christian Lindenmeier, Jonas Röckl

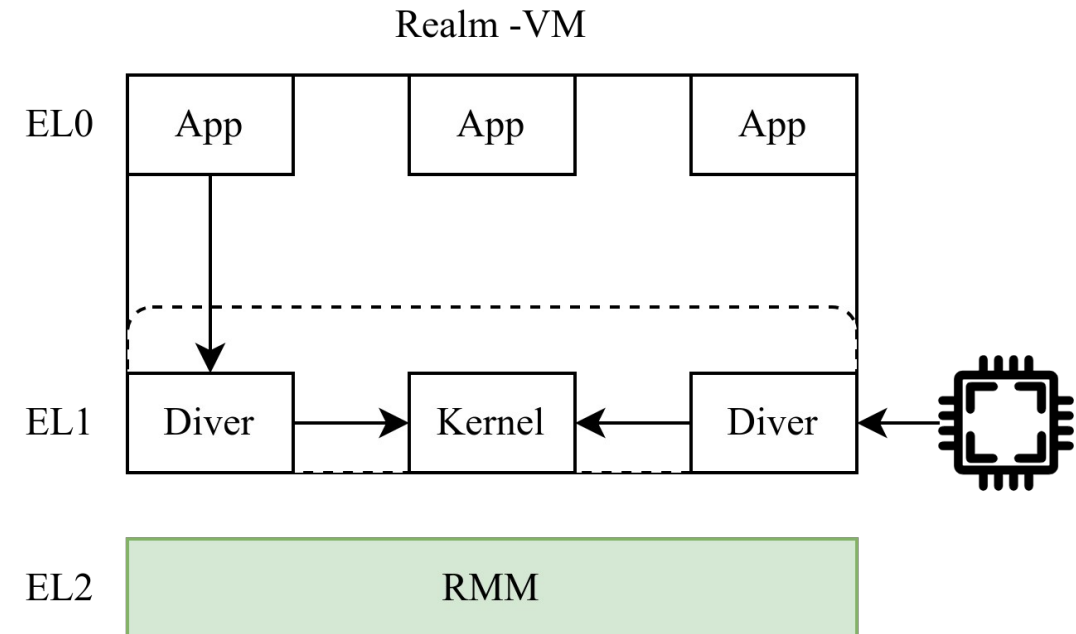
Friedrich-Alexander-Universität Erlangen-Nürnberg, Germany

ARM CCA



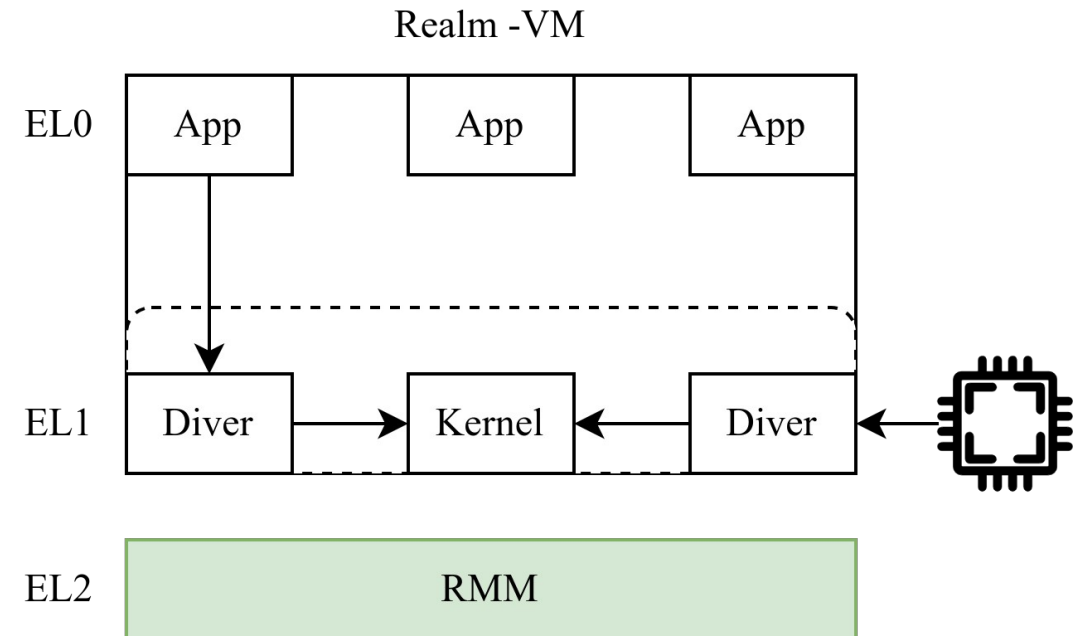
Attacker Model

- CCA offers protection from untrusted software running „outside“ the R-VM
- Attacker „inside“ the R-VM still a significant danger



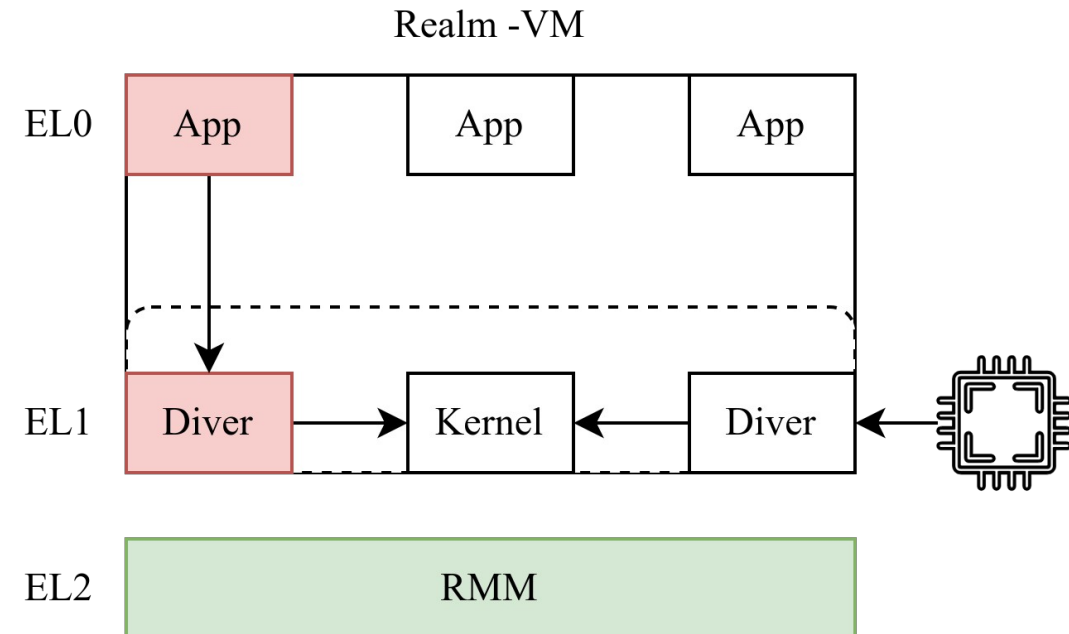
Attacker Model

- CCA offers protection from untrusted software running „outside“ the R-VM
- Attacker „inside“ the R-VM still a significant danger
- Most privilege escalations stem from vulnerable drivers



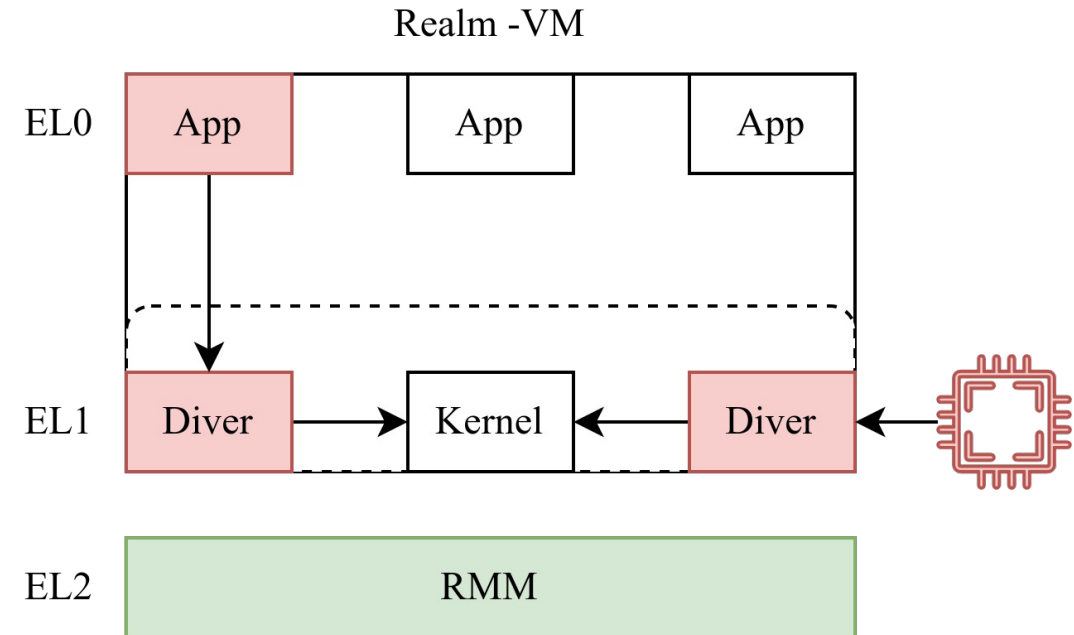
Attacker Model

- CCA offers protection from untrusted software running „outside“ the R-VM
- Attacker „inside“ the R-VM still a significant danger
- Most privilege escalations stem from vulnerable drivers
- Apps can exploit these vulnerabilities



Attacker Model

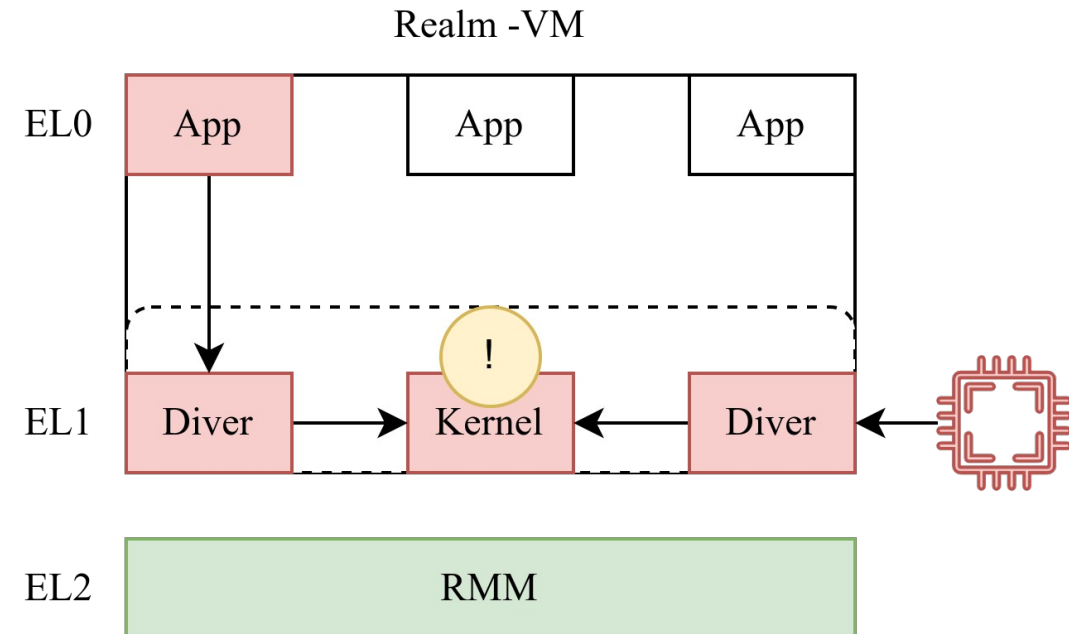
- CCA offers protection from untrusted software running „outside“ the R-VM
- Attacker „inside“ the R-VM still a significant danger
- Most privilege escalations stem from vulnerable drivers
- Apps can exploit these vulnerabilities
- Peripherals can trigger vulnerabilities



Attacker Model

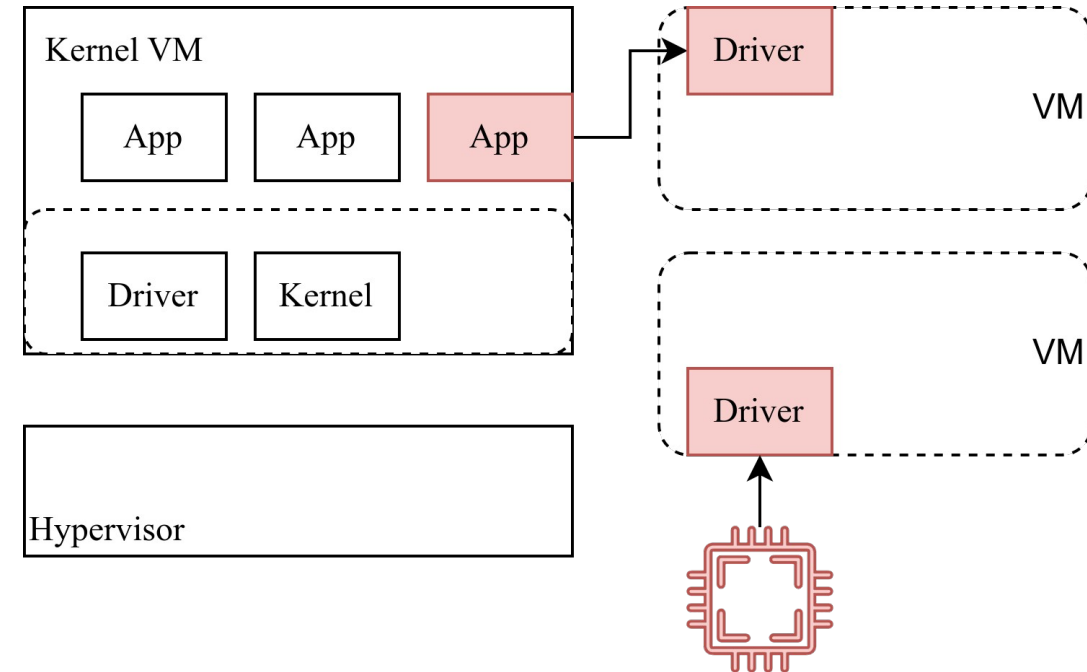
- CCA offers protection from untrusted software running „outside“ the R-VM
- Attacker „inside“ the R-VM still a significant danger
- Most privilege escalations stem from vulnerable drivers
- Apps can exploit these vulnerabilities
- Peripherals can trigger vulnerabilities

Monolithic Kernel => System Compromise



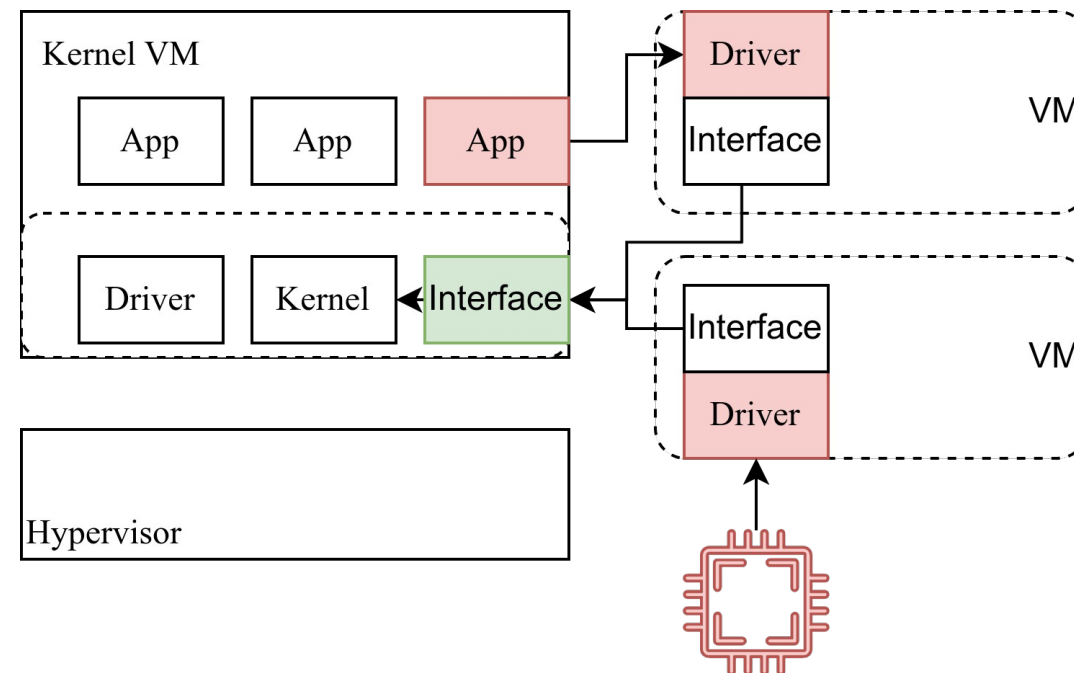
Challenges

- State of the art solutions isolate Drivers into VMs



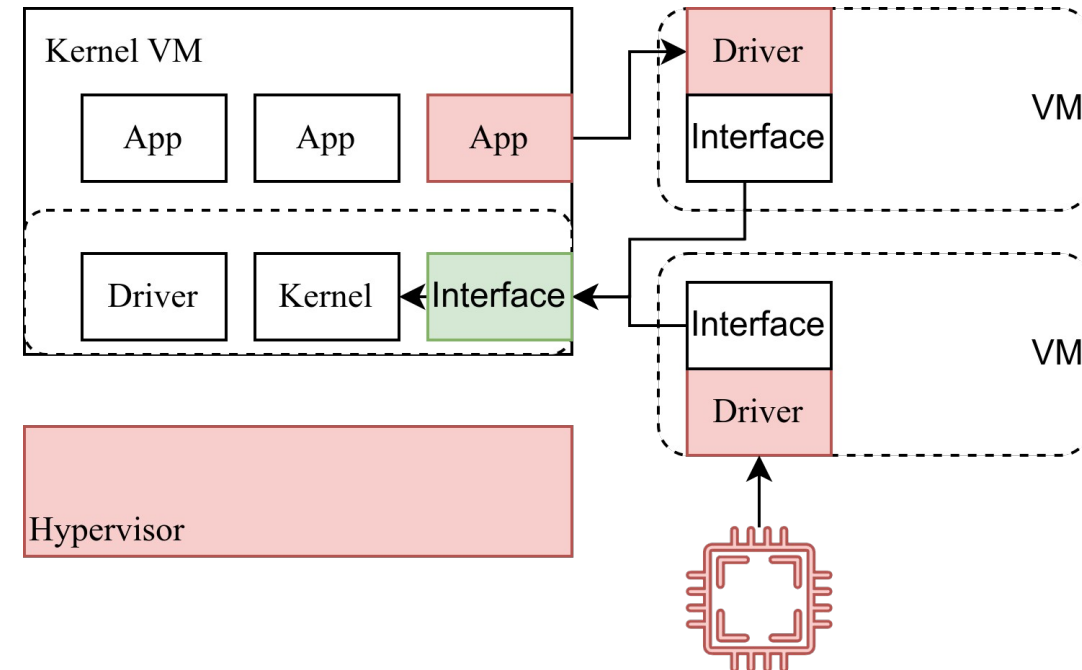
Challenges

- State of the art solutions isolate Drivers into VMs
- Add Interface to Drivers to communicate with the Kernel VM
 - Forward Kernel requests
 - Synchronize Resources



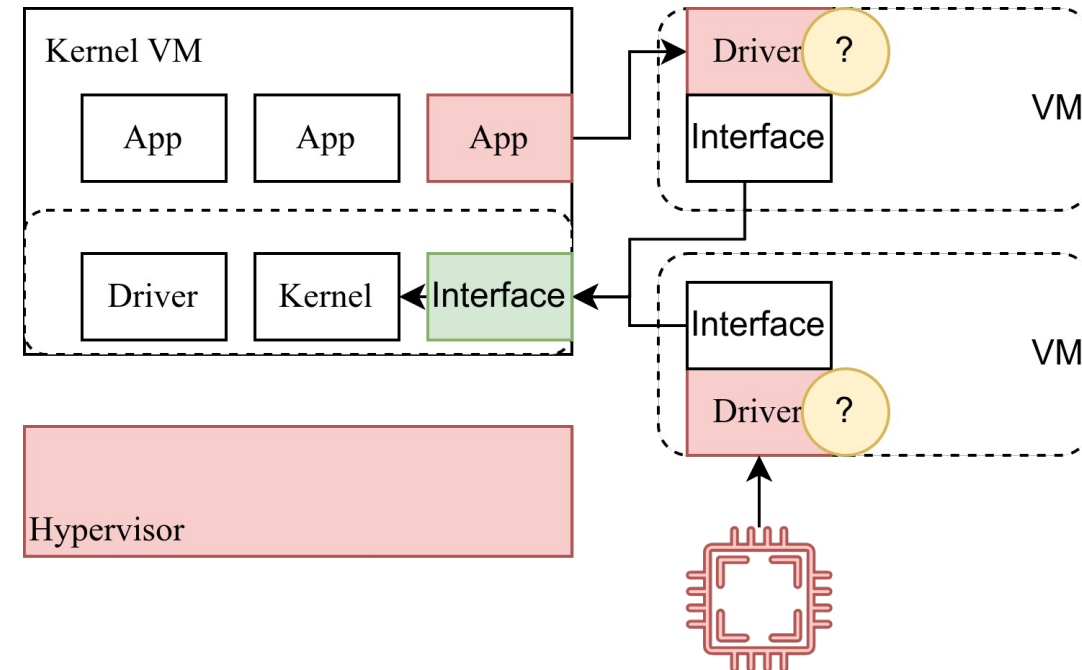
Challenges

- State of the art solutions isolate Drivers into VMs
- Add Interface to Drivers to communicate with the Kernel VM
 - Forward Kernel requests
 - Synchronize Resources
- Problems:
 - Adding Hypervisor to the TCB



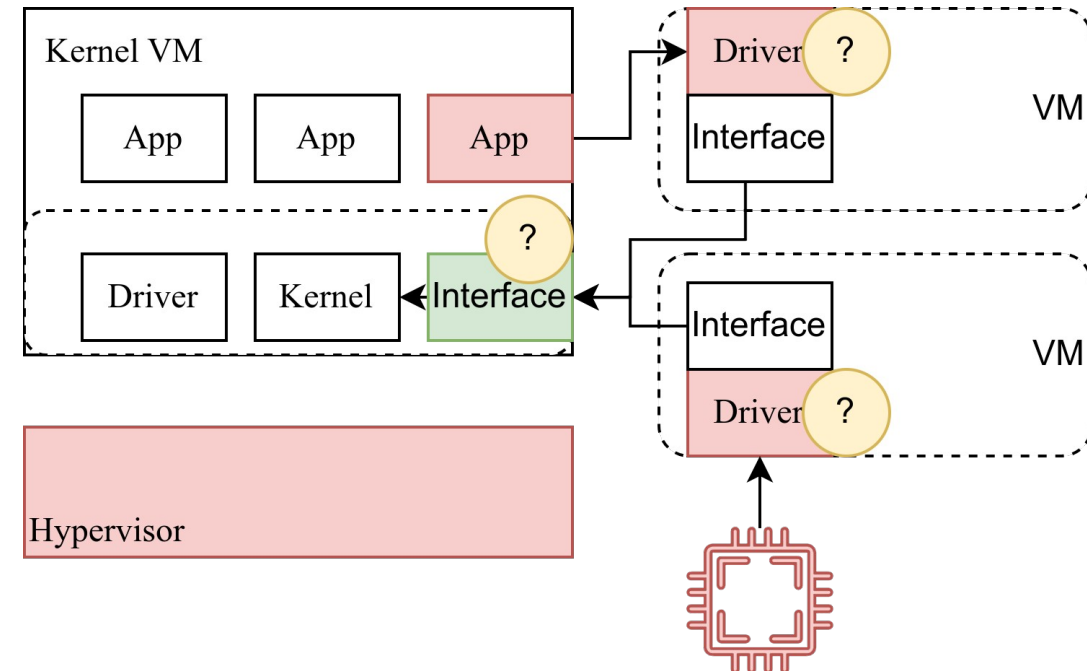
Challenges

- State of the art solutions isolate Drivers into VMs
- Add Interface to Drivers to communicate with the Kernel VM
 - Forward Kernel requests
 - Synchronize Resources
- Problems:
 - Adding Hypervisor to the TCB
 - What about closed-source Drivers?



Challenges

- State of the art solutions isolate Drivers into VMs
- Add Interface to Drivers to communicate with the Kernel VM
 - Forward Kernel requests
 - Synchronize Resources
- Problems:
 - Adding Hypervisor to the TCB
 - What about closed-source drivers?
 - How to actually filter out „evil“ requests?

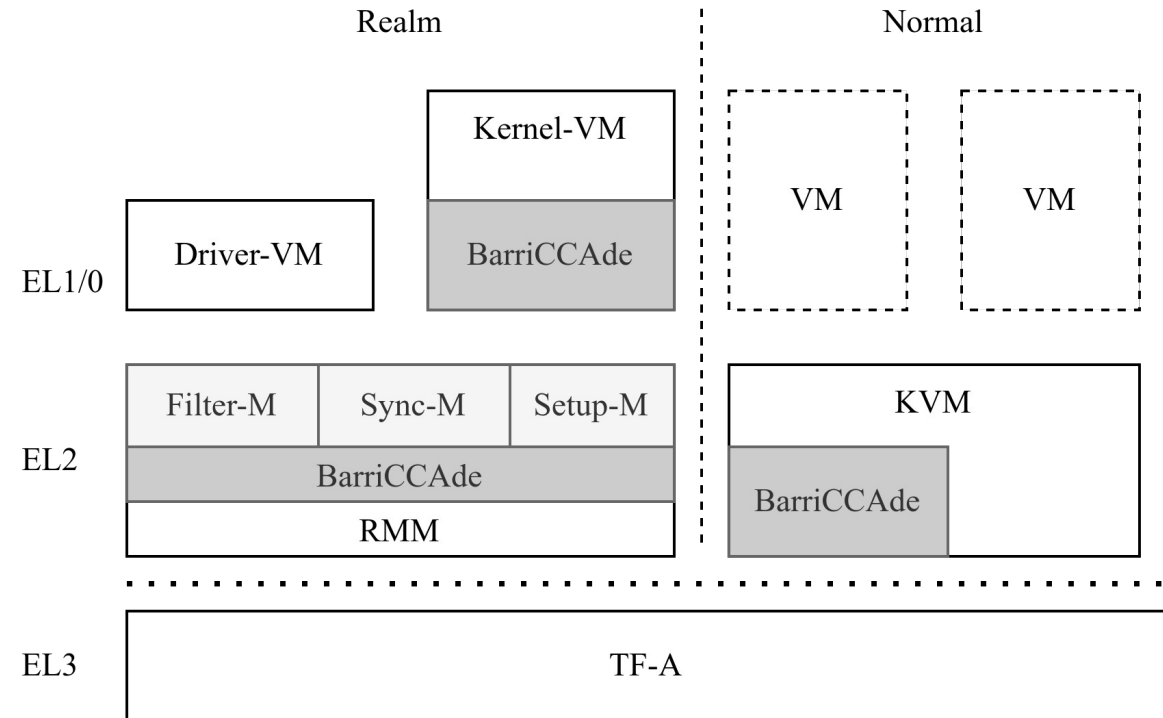


BarriCCAd



BarriCCAdede

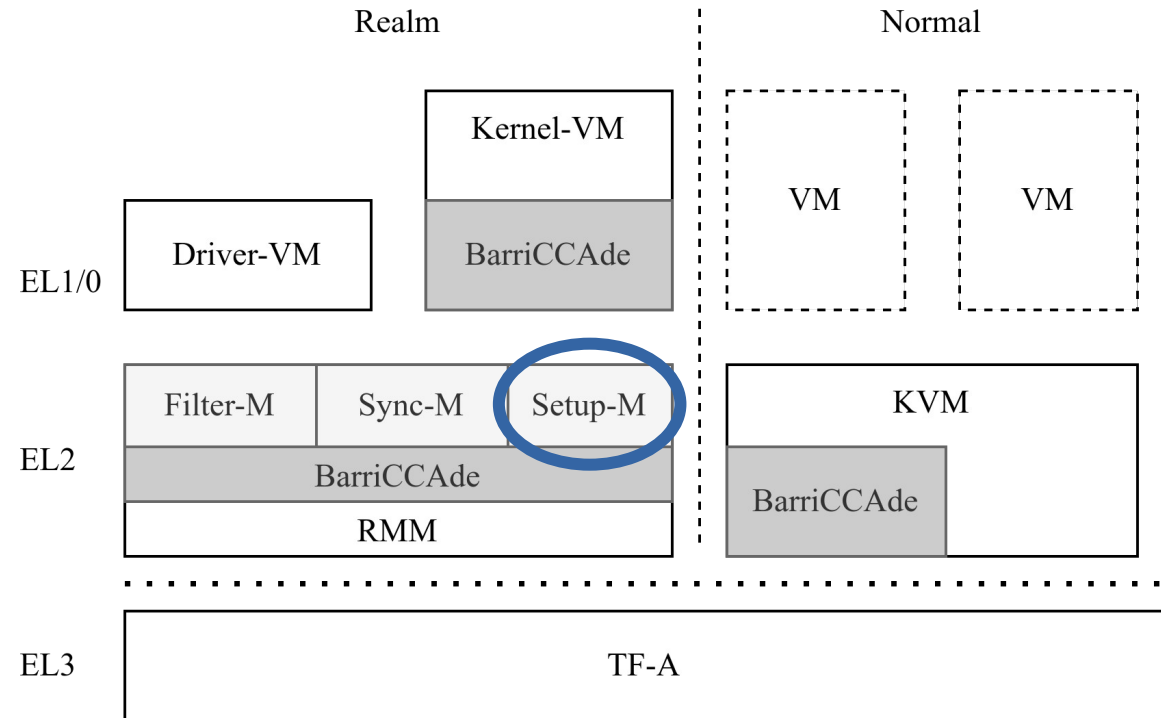
- Utilize CCA to not increase the TCB





BarriCCAd

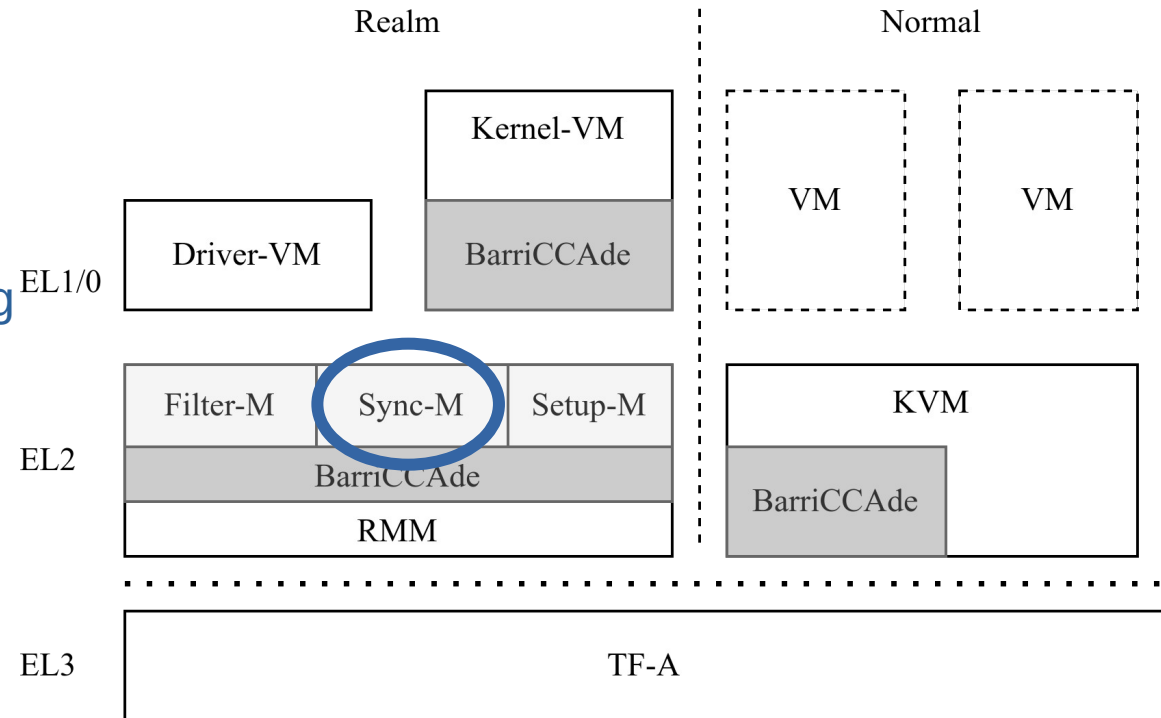
- Utilize CCA to not increase the TCB
- Expand the RMM to implement modules handling
 - The setup of Driver-VMs





BarriCCAd

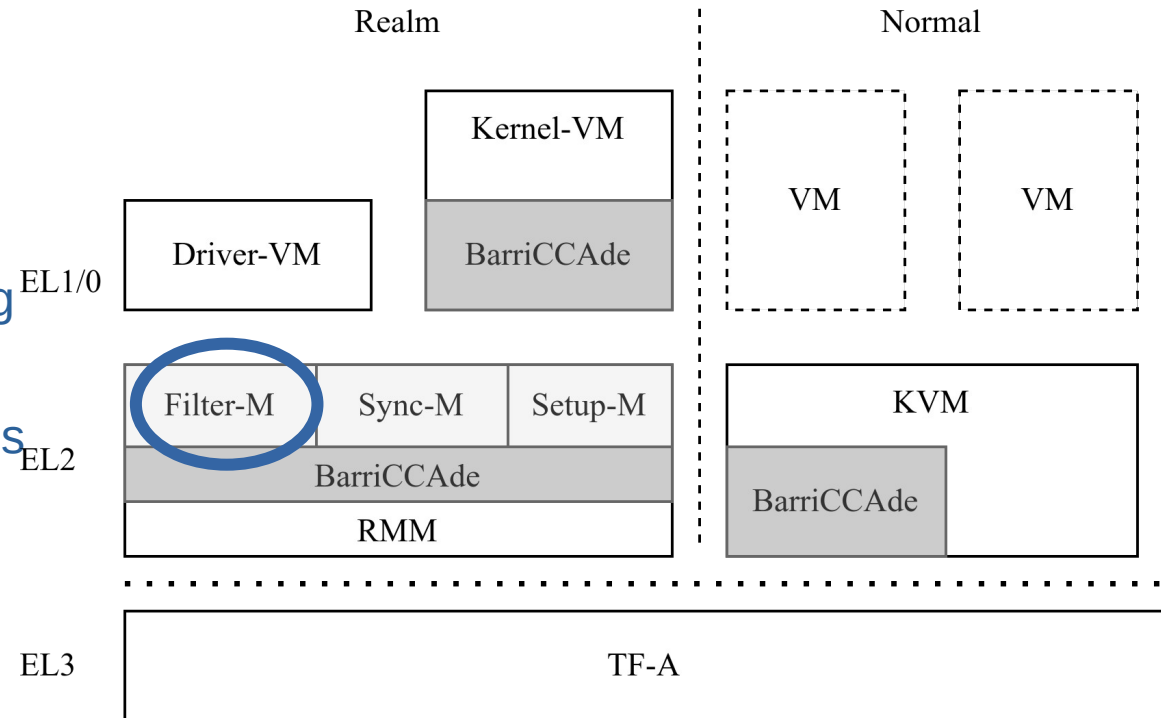
- Utilize CCA to not increase the TCB
- Expand the RMM to implement modules handling
 - The setup of Driver-VMs
 - The synchronization of resources including for closed-source drivers





BarriCCAd

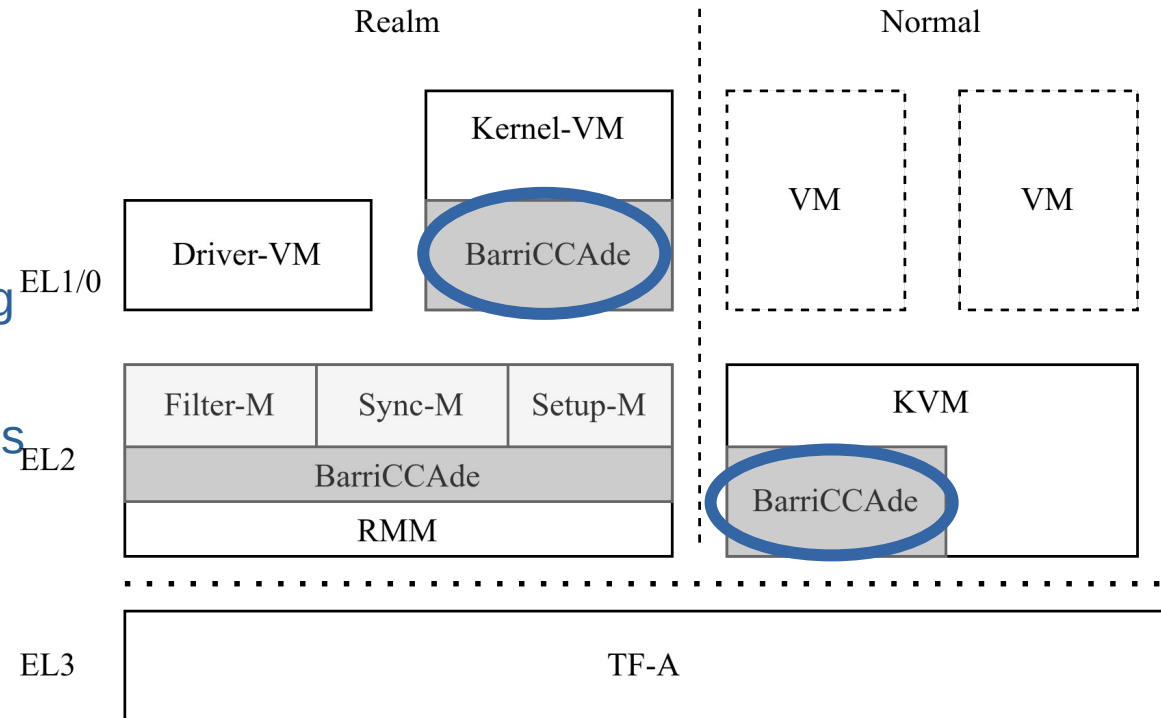
- Utilize CCA to not increase the TCB
- Expand the RMM to implement modules handling
 - The setup of Driver-VMs
 - The synchronization of resources including for closed-source drivers
 - Configurable filtering of malicious accesses





BarriCCAd

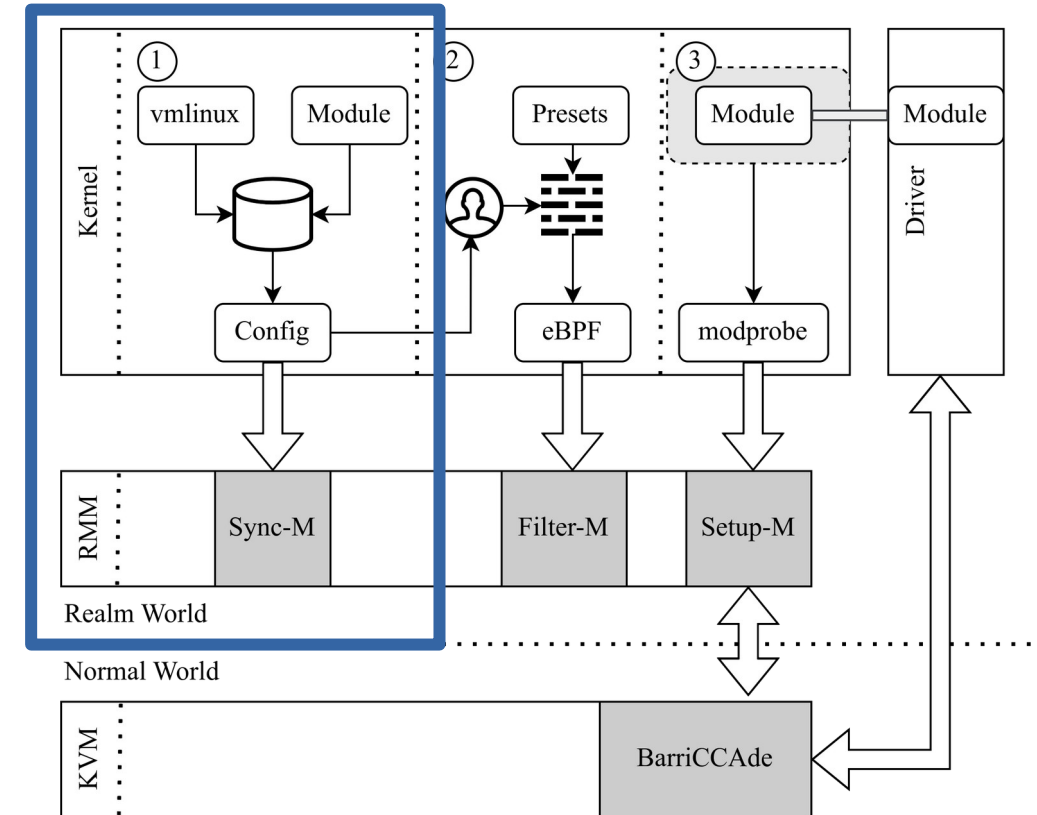
- Utilize CCA to not increase the TCB
- Expand the RMM to implement modules handling
 - The setup of Driver-VMs
 - The synchronization of resources including for closed-source drivers
 - Configurable filtering of malicious accesses
- Expand other untrusted components as needed



BarriCCAdo - Setup

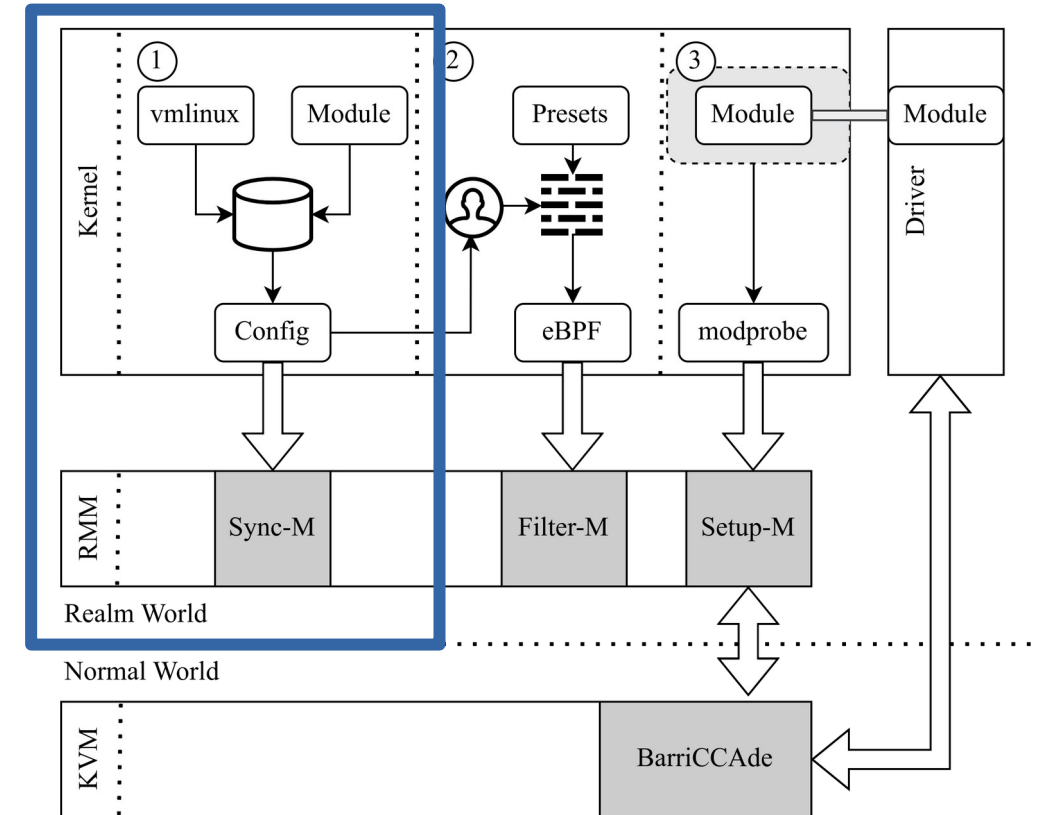
BarriCCAdé – Setup

- For resource synchronization memory locations, size and semantics of the resources must be understood



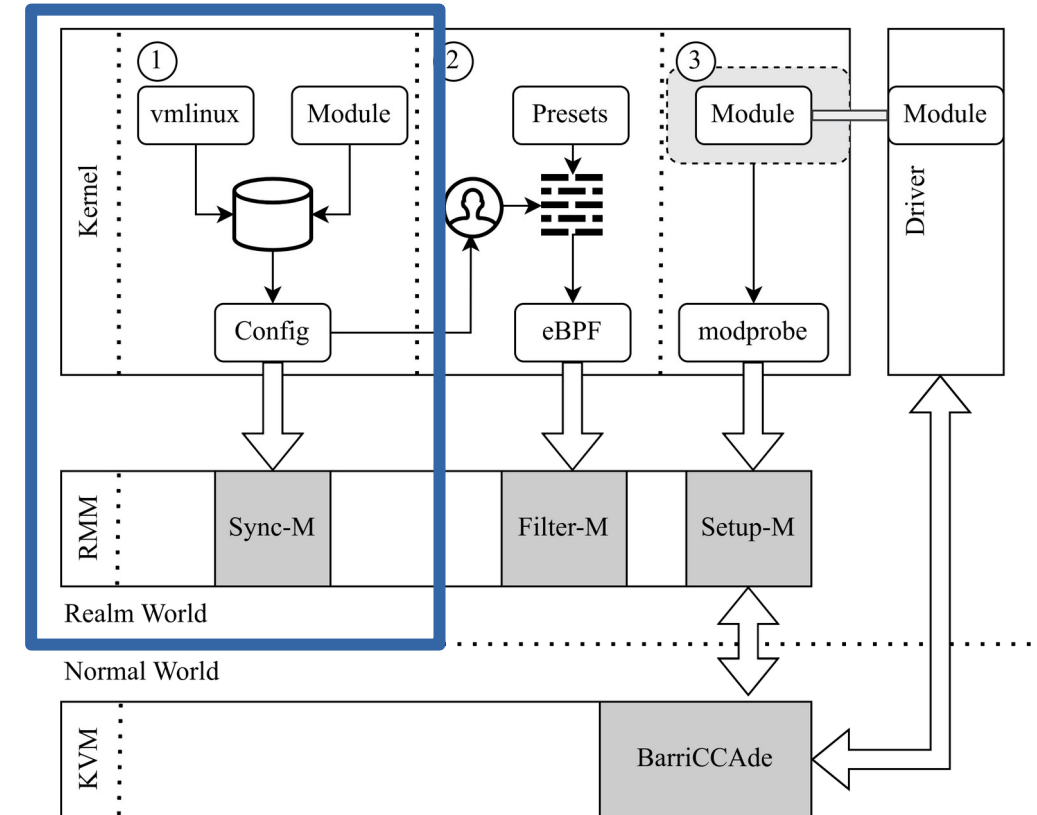
BarriCCAdé – Setup

- For resource synchronization memory locations, size and semantics of the resources must be understood
- Kernel creates **Sync-Config** by analyzing the used Kernel resources from the Driver ELF



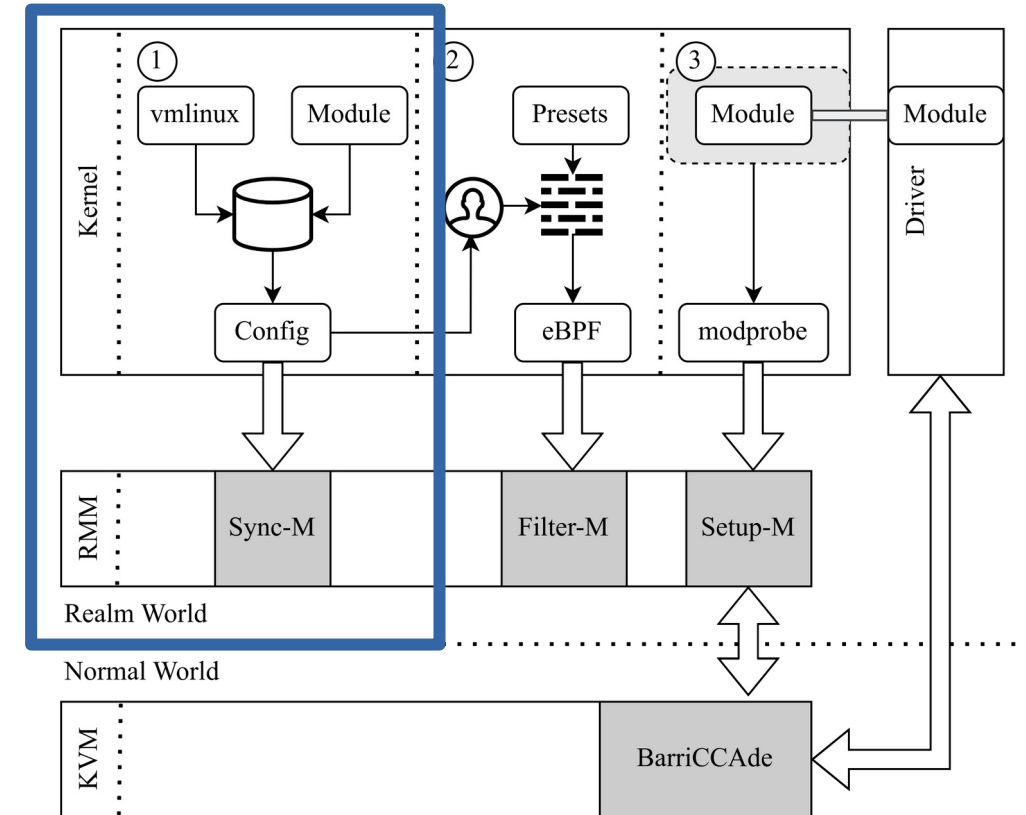
BarriCCAdé – Setup

- For resource synchronization memory locations, size and semantics of the resources must be understood
- Kernel creates **Sync-Config** by analyzing the used Kernel resources from the Driver ELF
- Matches resources to the debug information in the Kernel
 - Operands, size of operands, pointers, ...



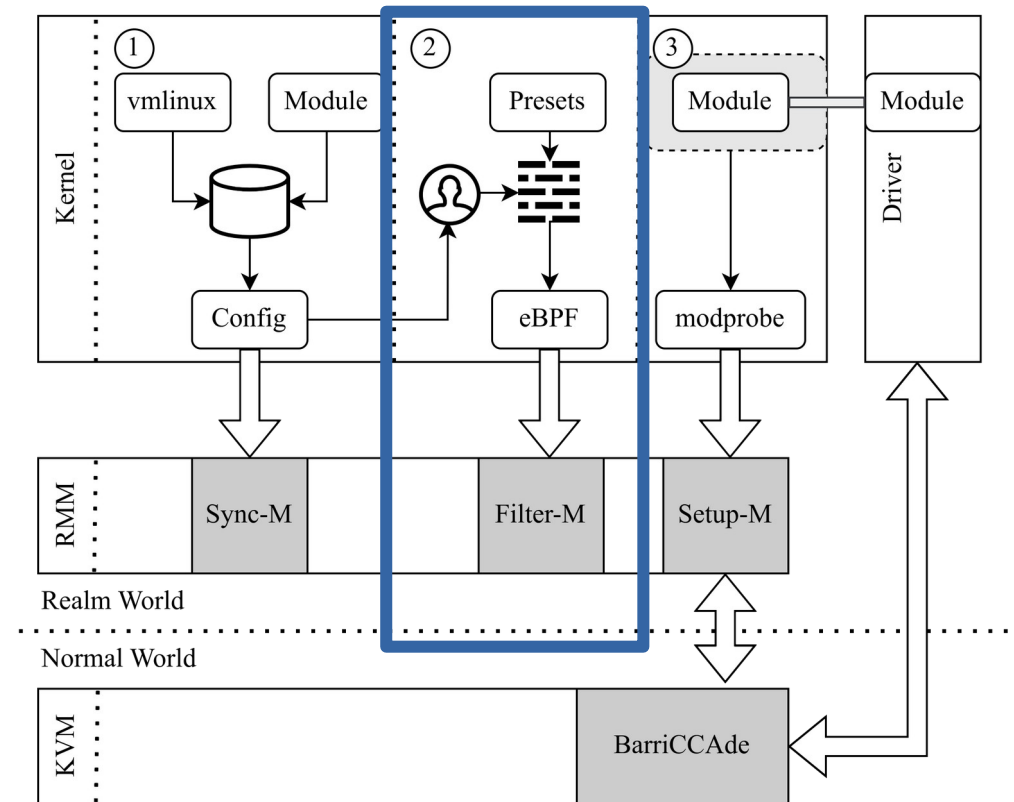
BarriCCAdé – Setup

- For resource synchronization memory locations, size and semantics of the resources must be understood
- Kernel creates **Sync-Config** by analyzing the used Kernel resources from the Driver ELF
- Matches resources to the debug information in the Kernel
 - Operands, size of operands, pointers, ...
- Evaluate recursively, load into **Sync-M**



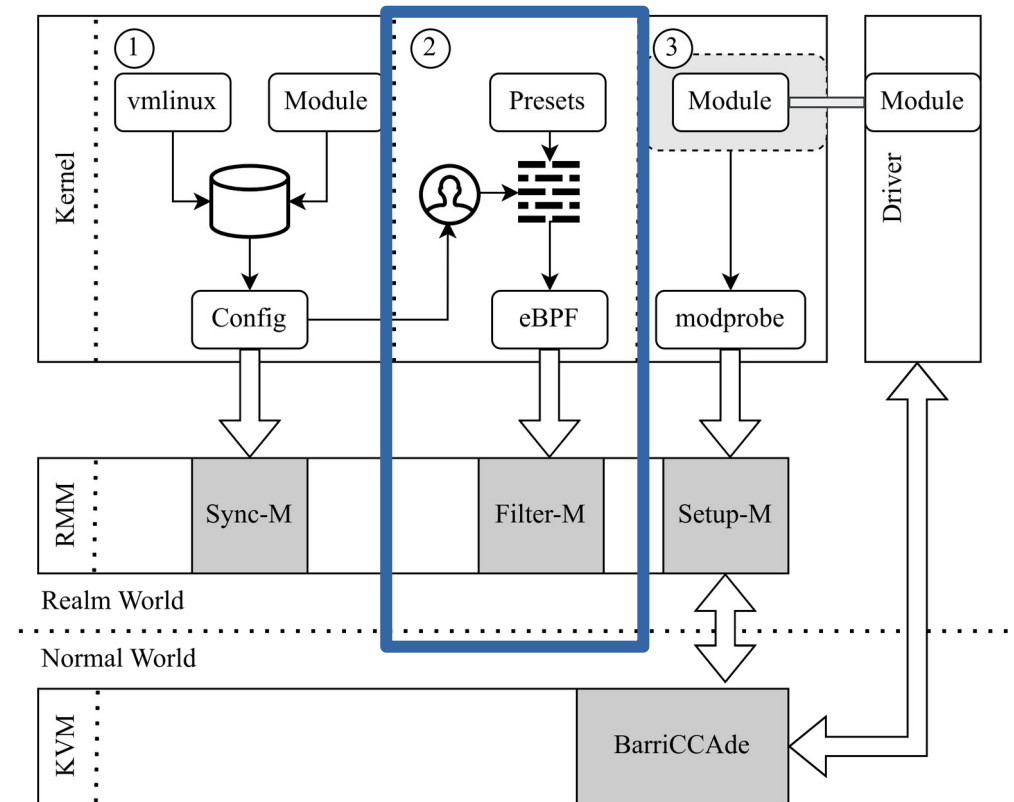
BarriCCAdé – Setup

- Config gives hint how to filter accesses
 - e.g., prevent access to task structs
 - e.g., prevent access to resources not listed in the config
 - ...



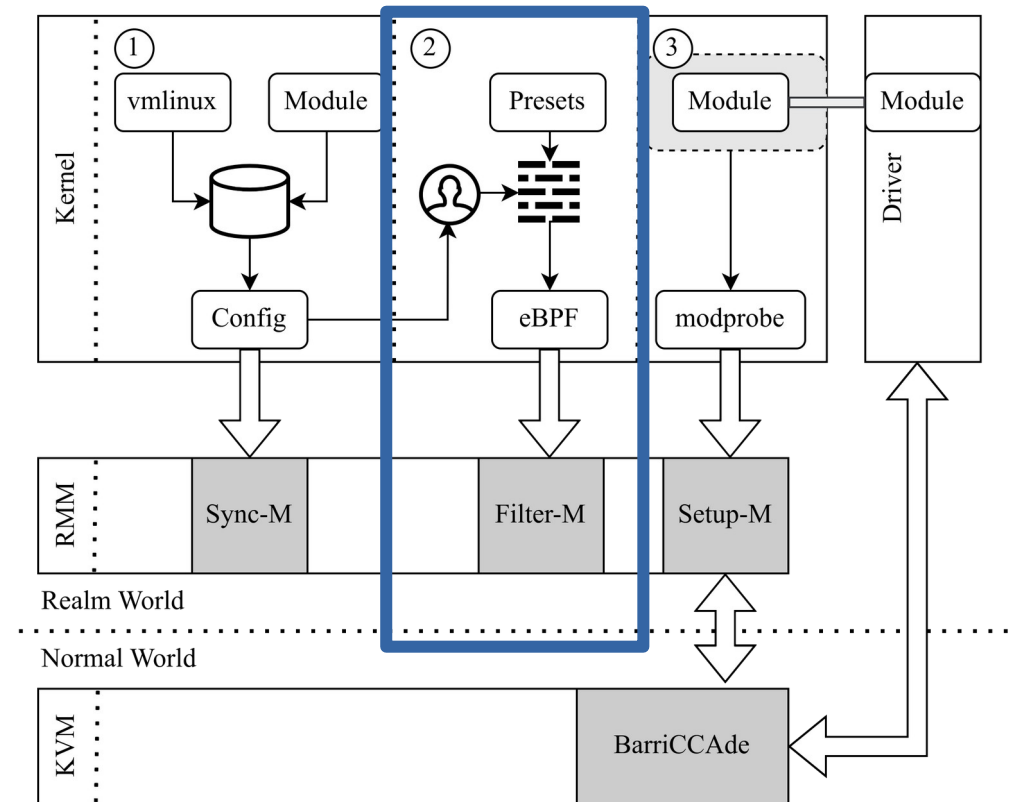
BarriCCAdé – Setup

- Config gives hint how to filter accesses
 - e.g., prevent access to task structs
 - e.g., prevent access to resources not listed in the config
 - ...
- Manual effort



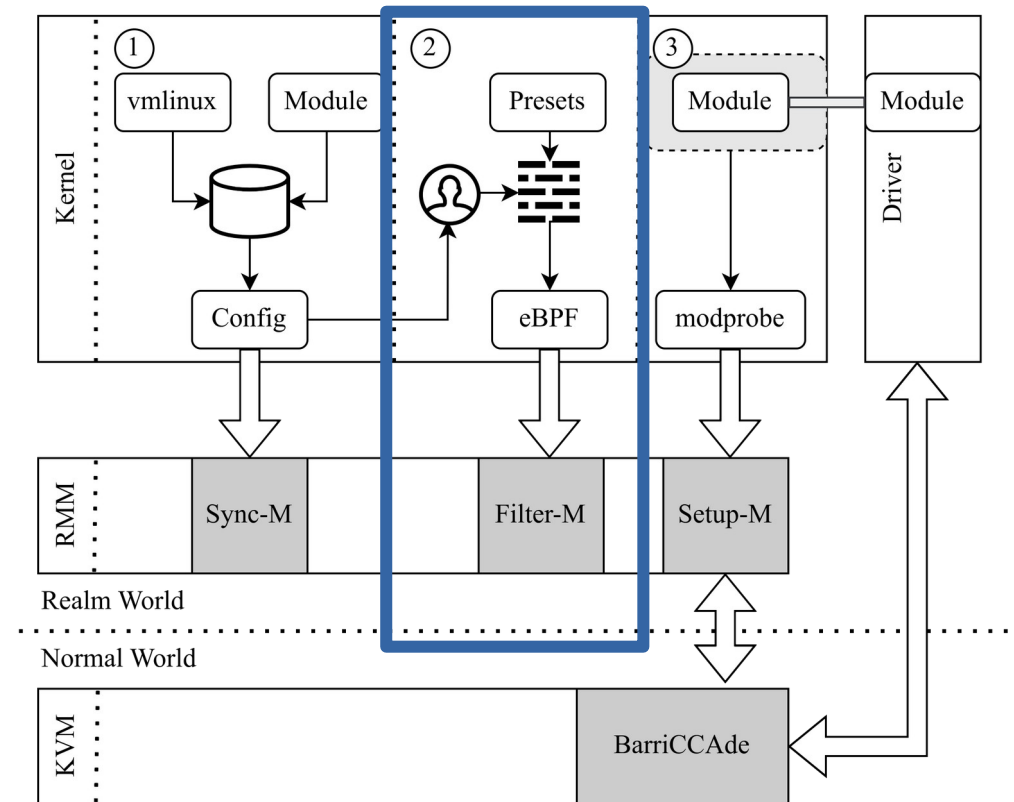
BarriCCAdé – Setup

- Config gives hint how to filter accesses
 - e.g., prevent access to task structs
 - e.g., prevent access to resources not listed in the config
 - ...
- Manual effort
- Vendor provided



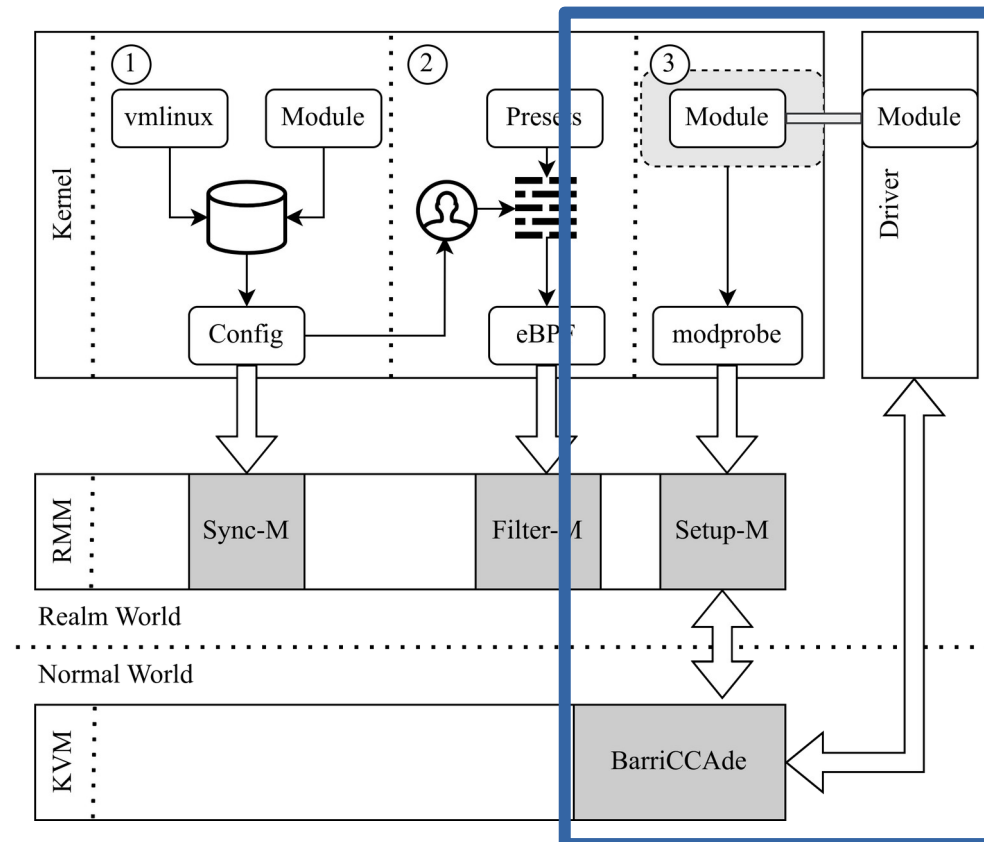
BarriCCAdé – Setup

- Config gives hint how to filter accesses
 - e.g., prevent access to task structs
 - e.g., prevent access to resources not listed in the config
 - ...
- Manual effort
- Vendor provided
- Compile into eBPF Program and load into **Filter-M**



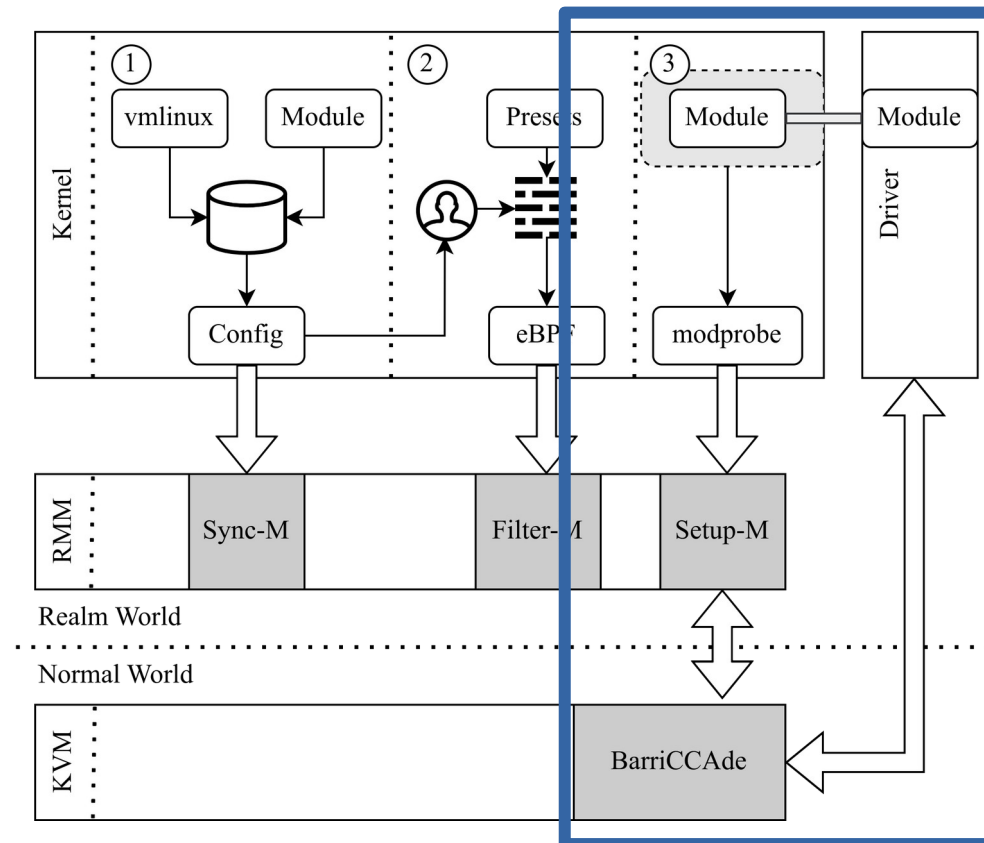
BarriCCAdé – Setup

- Load module via modprobe



BarriCCAdé – Setup

- Load module via modprobe
- Forward bounds to **Setup-M**
 - Creates Driver-VM



BarriCCAdé - Runtime



BarriCCAdé – Runtime

- At runtime, requests for Kernel/Driver resources must be forwarded accordingly



BarriCCAdé – Runtime

- At runtime, requests for Kernel/Driver resources must be forwarded accordingly
- Usually done via software added to the Driver
 - => What about a closed source scenario?



BarriCCAdé – Runtime

- At runtime, requests for Kernel/Driver resources must be forwarded accordingly
- Usually done via software added to the Driver
 - => What about a closed source scenario?
- Mark module pages in kernel as inaccessible via the RMM
 - => Accesses trapped to RMM



BarriCCAdo – Runtime

- At runtime, requests for Kernel/Driver resources must be forwarded accordingly
- Usually done via software added to the Driver
 - => What about a closed source scenario?
- Mark module pages in kernel as inaccessible via the RMM
 - => Accesses trapped to RMM
- Copy Driver after relocation
 - => Kernel resources not mapped
 - => Accesses trapped to RMM

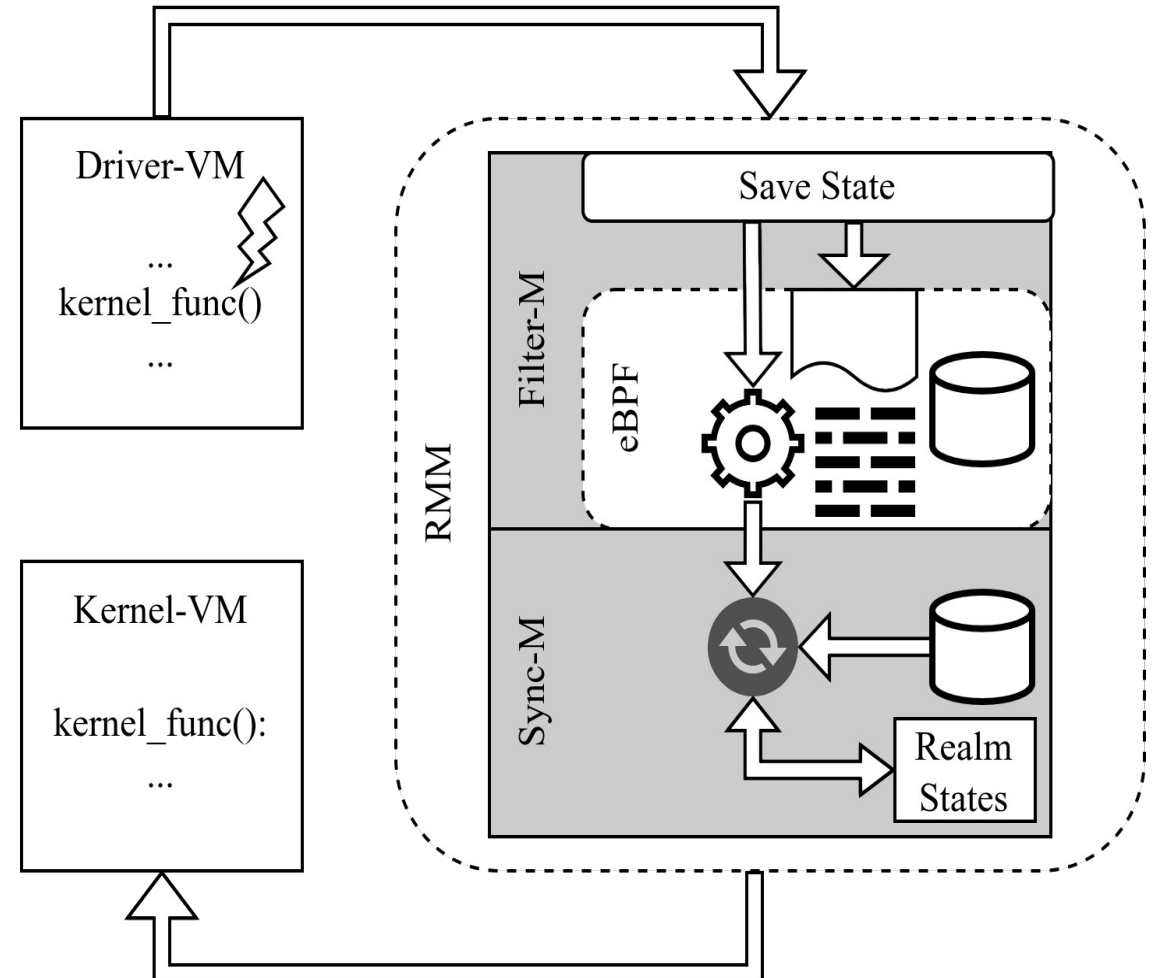


BarriCCAdé – Runtime

- At runtime, requests for Kernel/Driver resources must be forwarded accordingly
- Usually done via software added to the Driver
 - => What about a closed source scenario?
- Mark module pages in kernel as inaccessible via the RMM
 - => Accesses trapped to RMM
- Copy Driver after relocation
 - => Kernel resources not mapped
 - => Accesses trapped to RMM
- Trap context contains address accessed and state of the VM (e.g., params in registers)
 - => Implicitly contains all information needed for access forwarding

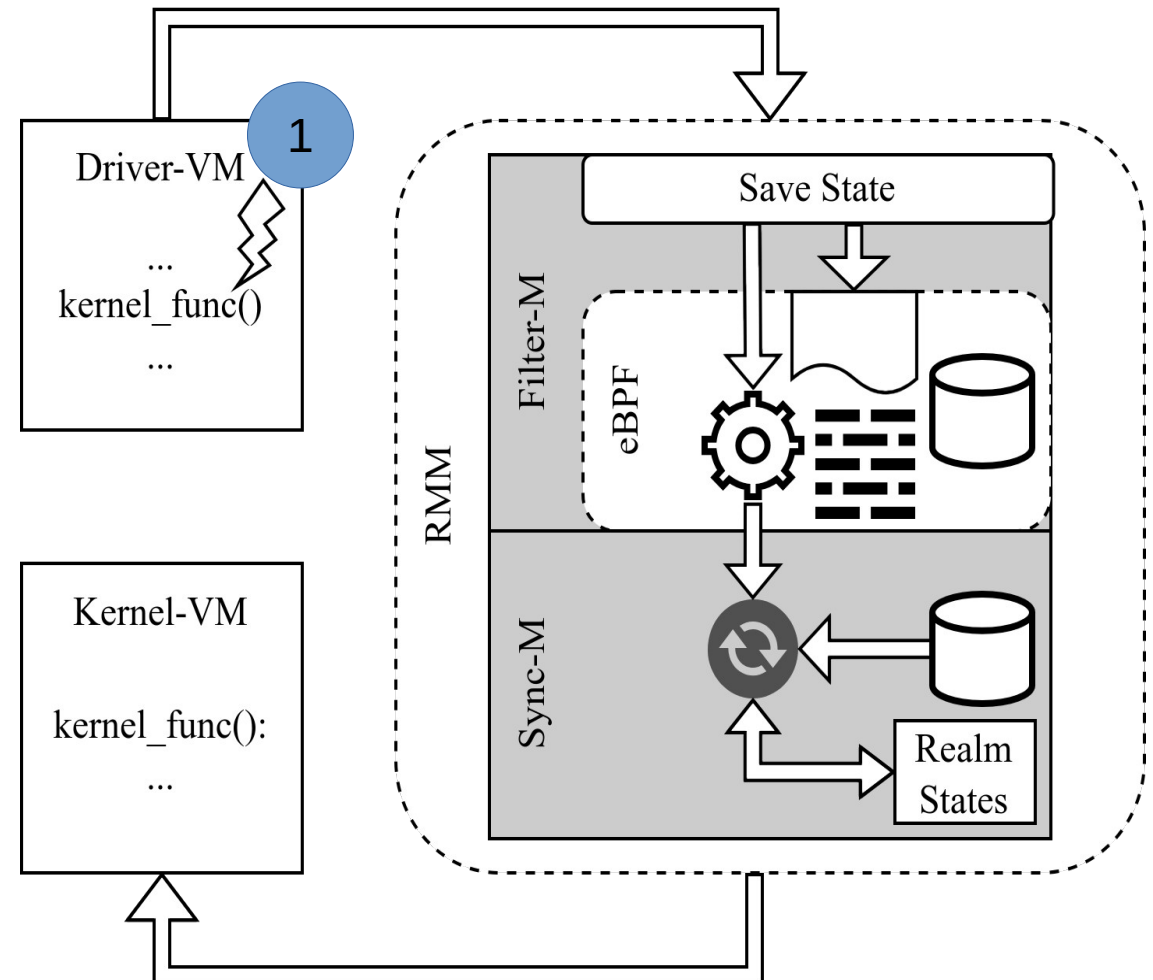
BarriCCAdé – Runtime

- Driver VM init function is called



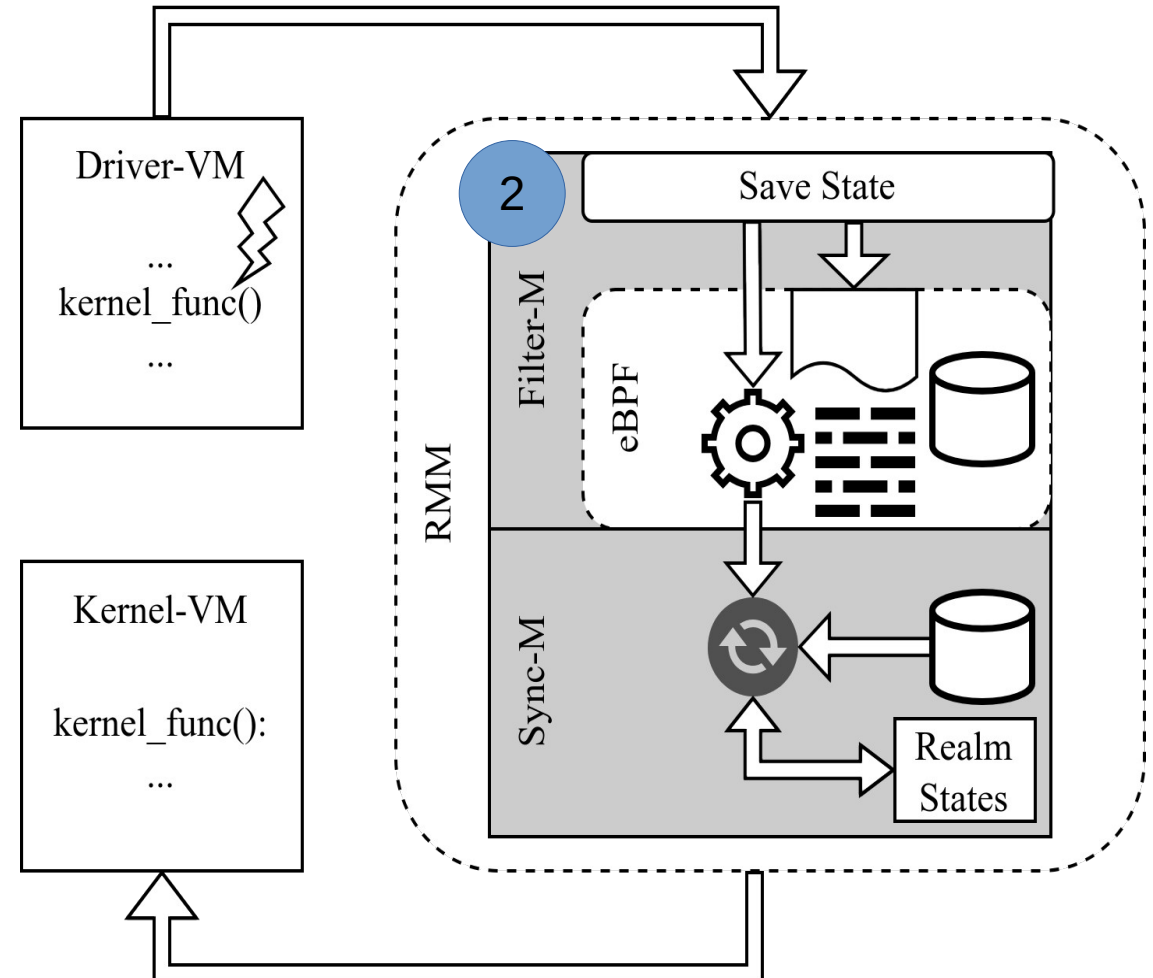
BarriCCAdé – Runtime

- Driver VM init function is called
- Access kernel function
 - => Not mapped
 - => Trap to RMM



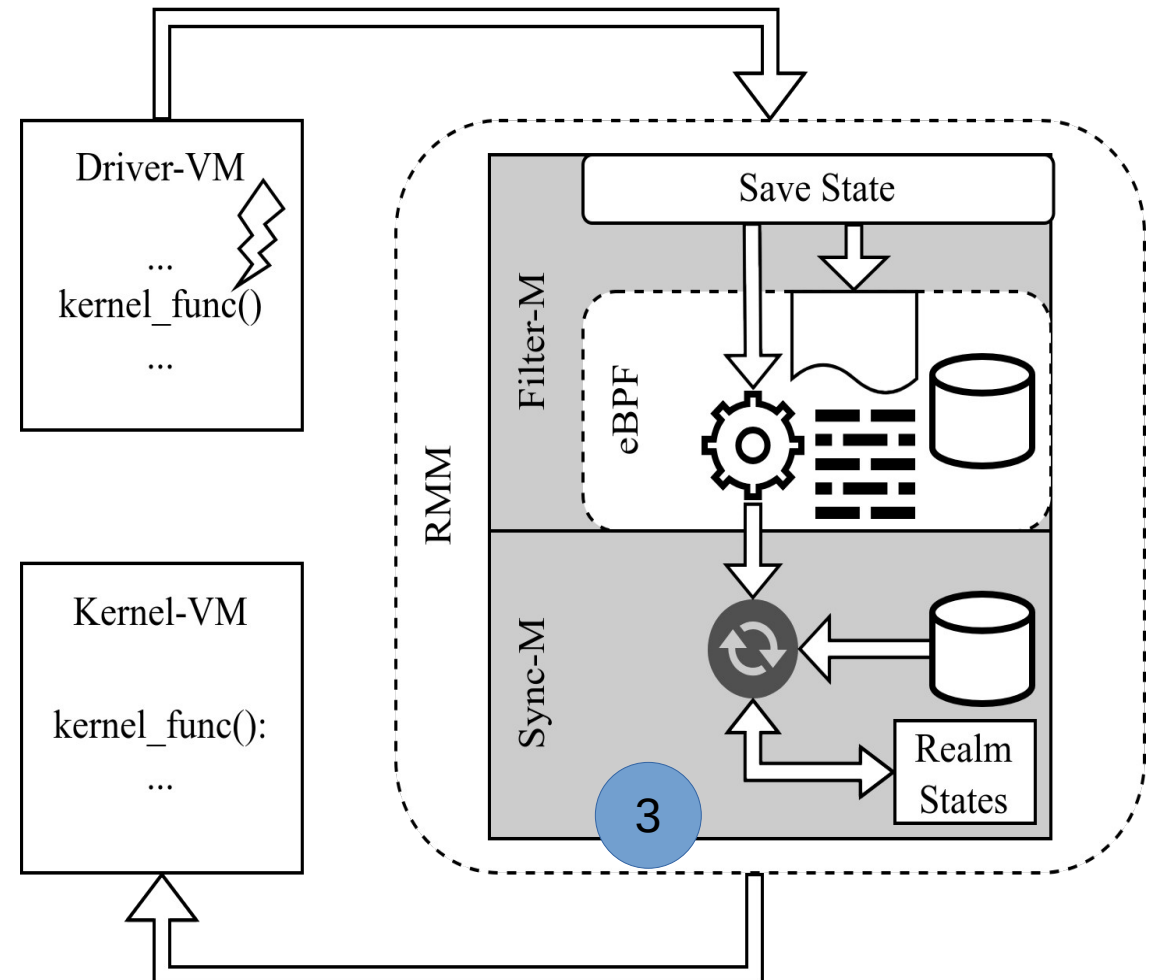
BarriCCAdé – Runtime

- Driver VM init function is called
- Access kernel function
 - => Not mapped
 - => Trap to RMM
- Forward state, filter rules, config to the eBPF program



BarriCCAdé – Runtime

- Extract information for accessed resource from sync config
- Synchronize resources according to config to kernel state





BarriCCAdé – Status and Outlook

- Work in Progress
- eBPF Filter fully functional
- Basic Synchronization implemented
- Prototype can load and execute dummy modules
- So far 2195 LOC added to TCB (1722 formally verified eBPF Interpreter, 473 „untrusted“)
- Evaluation on real drivers TBD



BarriCCAdé – Status and Outlook

- Work in Progress
- eBPF Filter fully functional
- Basic Synchronization implemented
- Prototype can load and execute dummy modules
- So far 2195 LOC added to TCB (1722 formally verified eBPF Interpreter, 473 „untrusted“)
- Evaluation on real drivers TBD

- Improve (automatic) generation of Sync Configs
- Improve (automatic) generation of Filter Rules

Summary

Thanks for your attention!



BarriCCAd: Isolating Closed-Source Drivers with ARM CCA

Matti Schulze
FAU Erlangen-Nürnberg
matti.schulze@fau.de

Christian Lindenmeier
FAU Erlangen-Nürnberg
christian.lindenmeier@fau.de

Jonas Röckl
FAU Erlangen-Nürnberg
jonas.roeckl@fau.de

- BarriCCAd is a step forward to isolating vulnerable drivers
- Introduces novel resource synchronization technique based on debug information and trap based access forwarding to target closed source drivers
- Allows detection and blocking of malicious behavior via eBPF-based filters
- Minimal TCB increase by relying on novel Confidential Computing Architectures